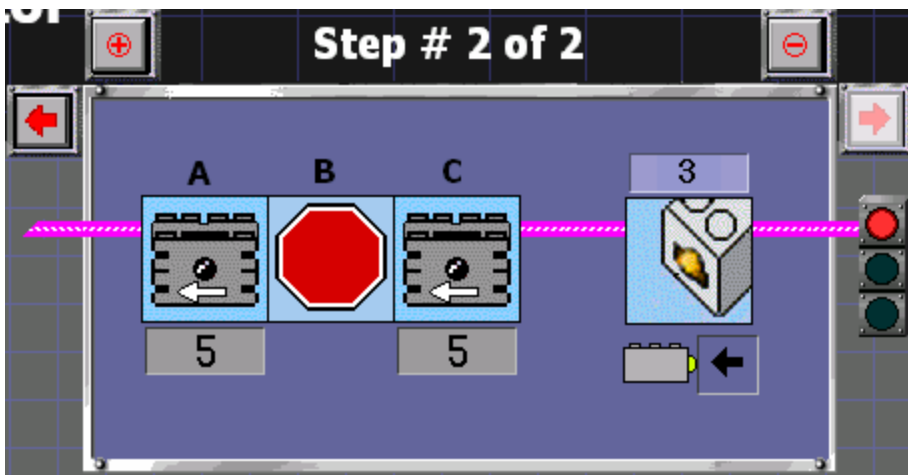
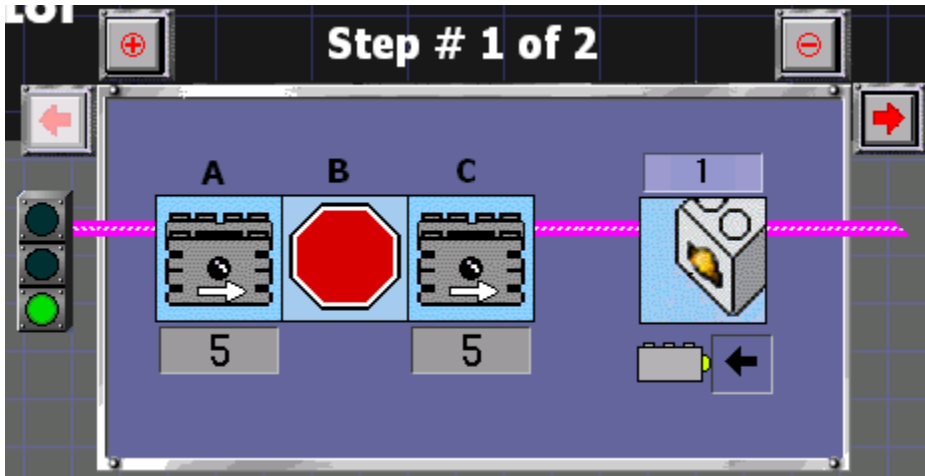
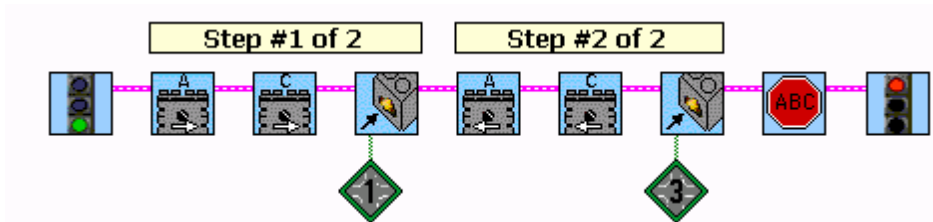


There and Back: Using Touch Sensors

Pilot version:



Inventor version:



This program makes the Robot go forward until the Touch Sensor on Input Port 1 is pressed. It then reverses the motors until the Touch Sensor on Input Port 3 is pressed, then it stops all Output Ports.